

Jet Classification – A comparison Between BDT, CNN, Transformers

Group – 5

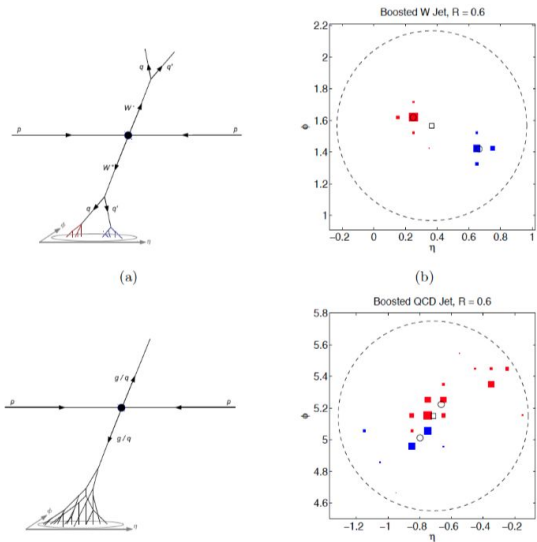
Jaideep Kalani, Arkodip Biswas, Ankan Roy, Abhishek MS,
Rajesh Pramanik, Sarthak Tripathy

Guide - Saranya Samik Ghosh



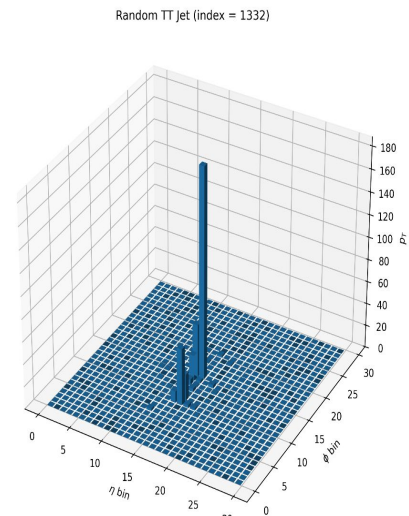
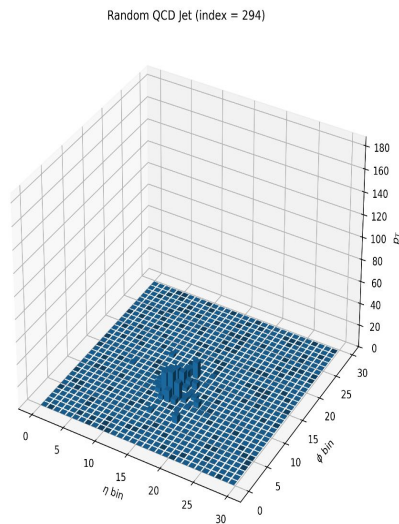
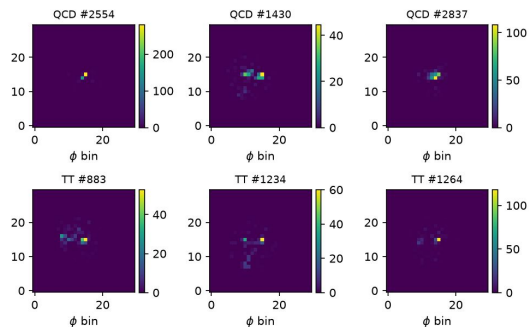
Jets As Images

<https://cs229.stanford.edu/proj2013/Anenberg-WsQCDJetTaggingatLHC.pdf>

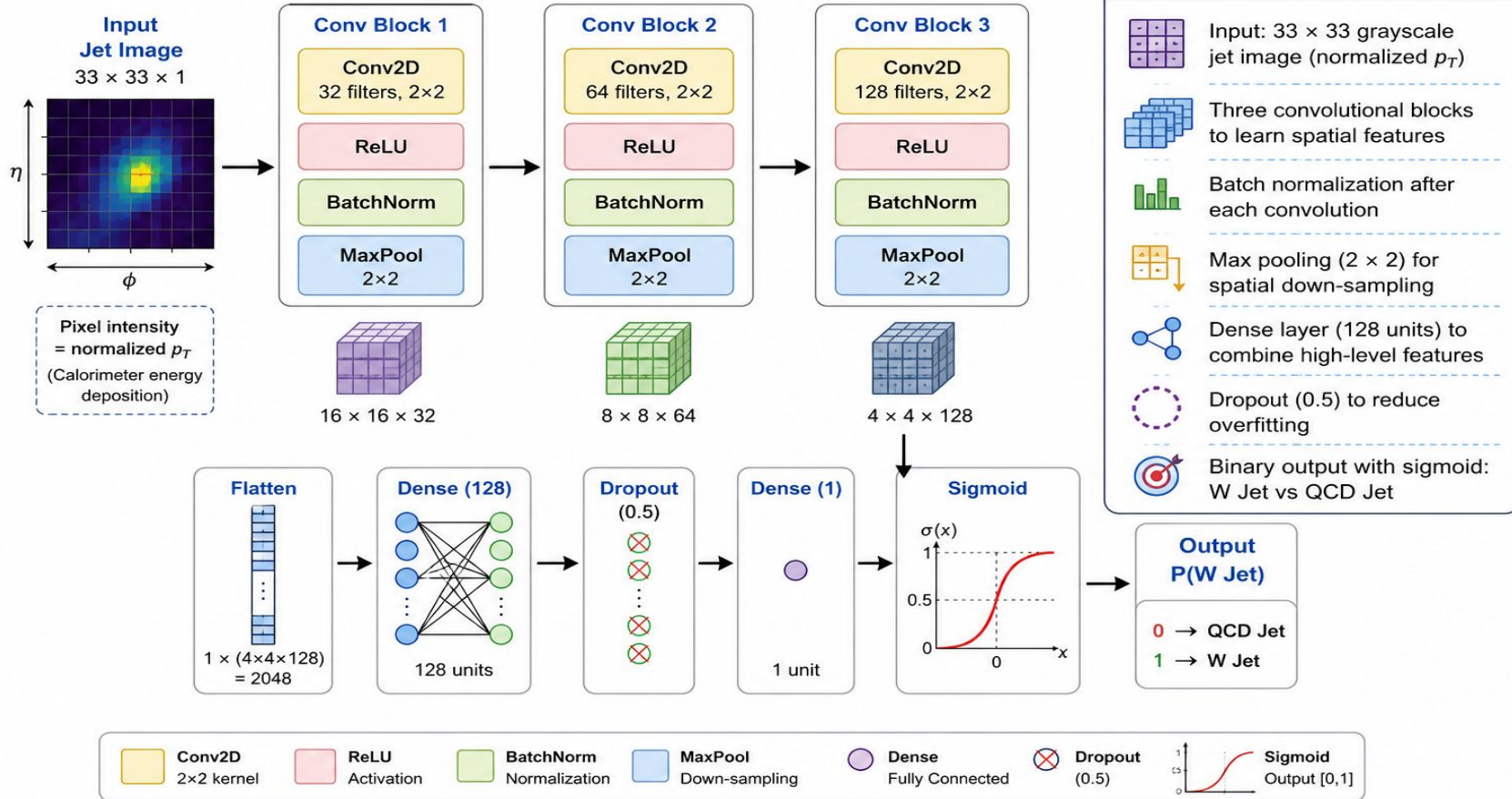


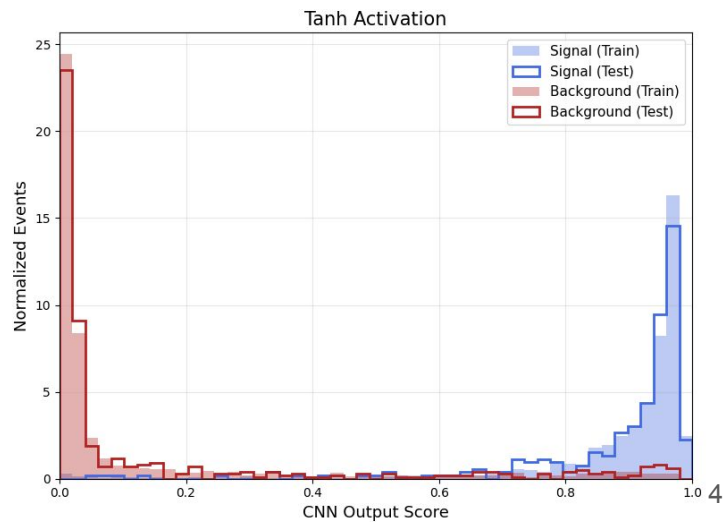
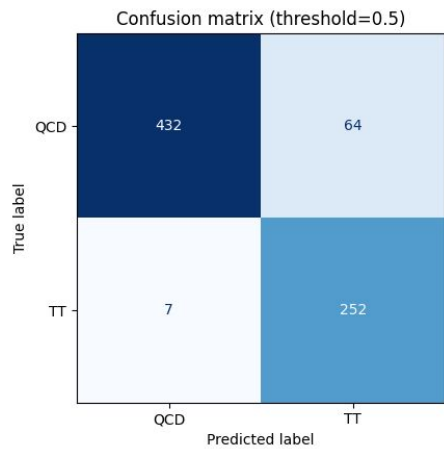
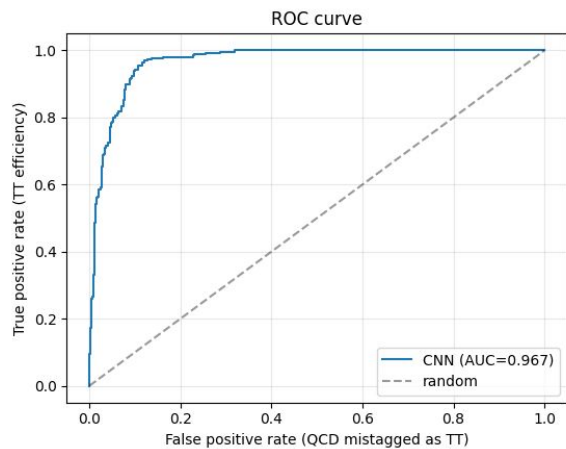
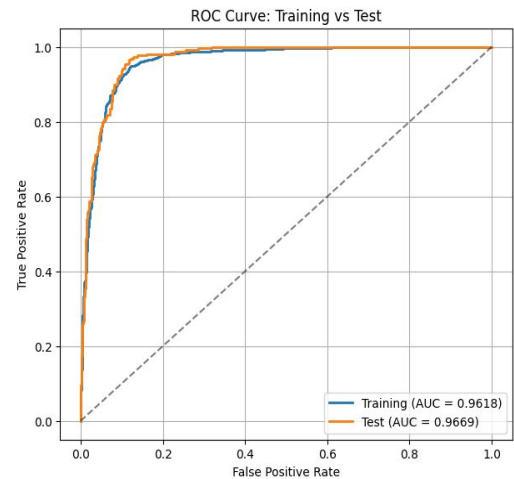
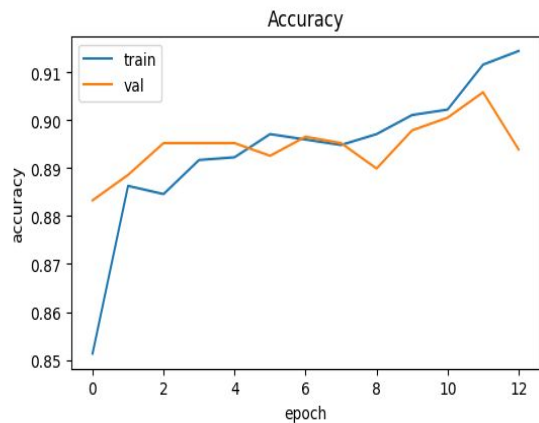
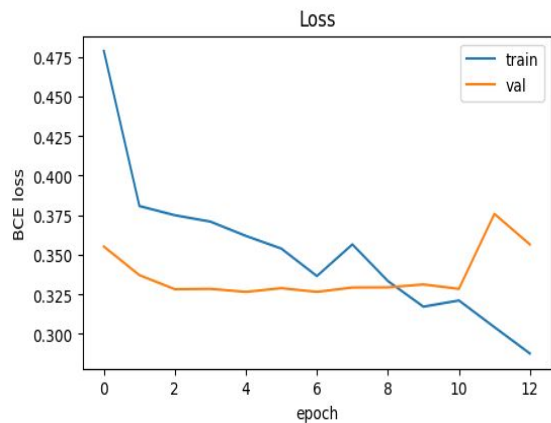
➤ The goal of the project is to discriminate between jets that originate from boosted W-boson and QCD

Sample jet images (pixel intensity = p_T)

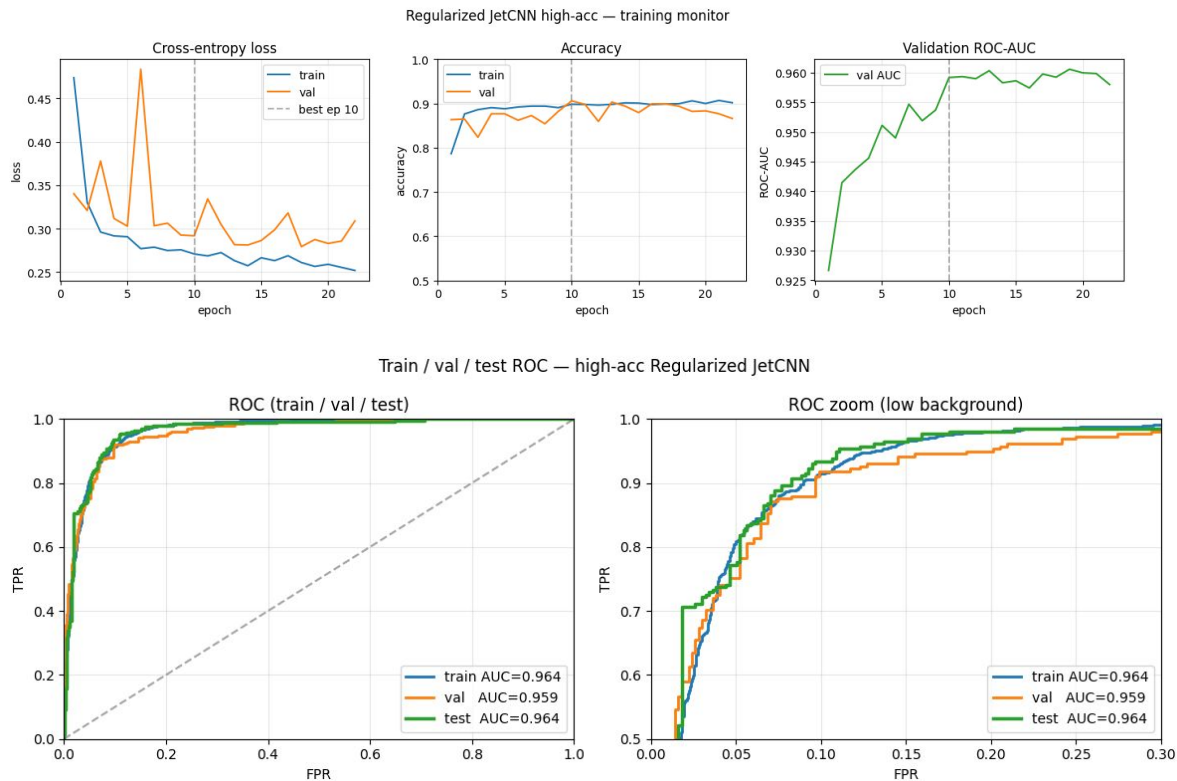


CNN - Architecture





Architecture 2



RegularizedJetCNNHighAcc Architecture

High-Accuracy Regularized CNN for Jet Tagging

Input: Jet Image

(1 × 30 × 30)



ConvBlock 0

- Conv2d(1 ~ 32, 3*3, padding=1, bias=False)
- BatchNorm2d(32)
- ReLU(inplace=True)
- MaxPool2d(2*2)
- Dropout2d(p=0.05)

Spatial: 30×30 × 15×15

ConvBlock 1

- Conv2d(32 × 64, 3*3, padding=1, bias=False)
- BatchNorm2d(64)
- ReLU(inplace=True)
- MaxPool2d(2*2)
- Dropout2d(p=0.05)

Spatial: 15×15 × 7×7

Additional Convolutional Layers

- Conv2d(64 × 96, 3*3, padding=1, bias=False)
 - BatchNorm2d(96)
 - ReLU(inplace=True)
 - Conv2d(96 × 96, 3*3, padding=1, bias=False)
- Spatial remains ~7×7 (no pooling)

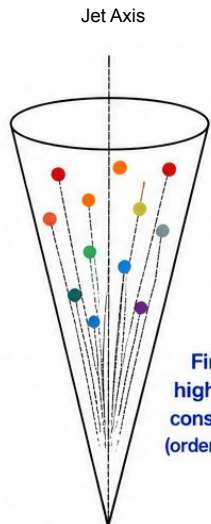
Classification Head

- AdaptiveAvgPool2d(1×1)
 - Flatten
 - Dropout(p=0.5)
 - Linear(96 × 2)
- Produces class logits

Output

Jets as Feature Vector

Variable	Definition
$\Delta\eta$	difference in pseudorapidity between the particle and the jet axis
$\Delta\phi$	difference in azimuthal angle between the particle and the jet axis
$\log p_T$	logarithm of the particle's p_T
$\log E$	logarithm of the particle's energy
$\log \frac{p_T}{p_T^{(\text{jet})}}$	logarithm of the particle's p_T relative to the jet p_T
$\log \frac{E}{E^{(\text{jet})}}$	logarithm of the particle's energy relative to the jet energy
ΔR	angular separation between the particle and the jet axis ($\sqrt{(\Delta\eta)^2 + (\Delta\phi)^2}$)



A jet is represented using the first 10 highest- p_T constituents
with 7 kinematic features per constituent

Constituent-level Features (7 per constituent)

Feature Name	η_{rel} (eta relative to jet axis)	ϕ_{rel} (phi relative to jet axis)	p_T (transverse momentum)	E (energy)	p_{Trel} (relative p_T to jet)	E_{rel} (relative energy to jet)	ΔR (distance from jet axis)
Column Index	8	11	5	3	6	4	13
Constituent Index (order)	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
1 (highest p_T)	η_{rel}^1	ϕ_{rel}^1	p_T^1	E^1	p_{Trel}^1	E_{rel}^1	ΔR^1
2	η_{rel}^2	ϕ_{rel}^2	p_T^2	E^2	p_{Trel}^2	E_{rel}^2	ΔR^2
3	η_{rel}^3	ϕ_{rel}^3	p_T^3	E^3	p_{Trel}^3	E_{rel}^3	ΔR^3
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\vdots$
10 (10th highest p_T)	η_{rel}^{10}	ϕ_{rel}^{10}	p_T^{10}	E^{10}	p_{Trel}^{10}	E_{rel}^{10}	ΔR^{10}

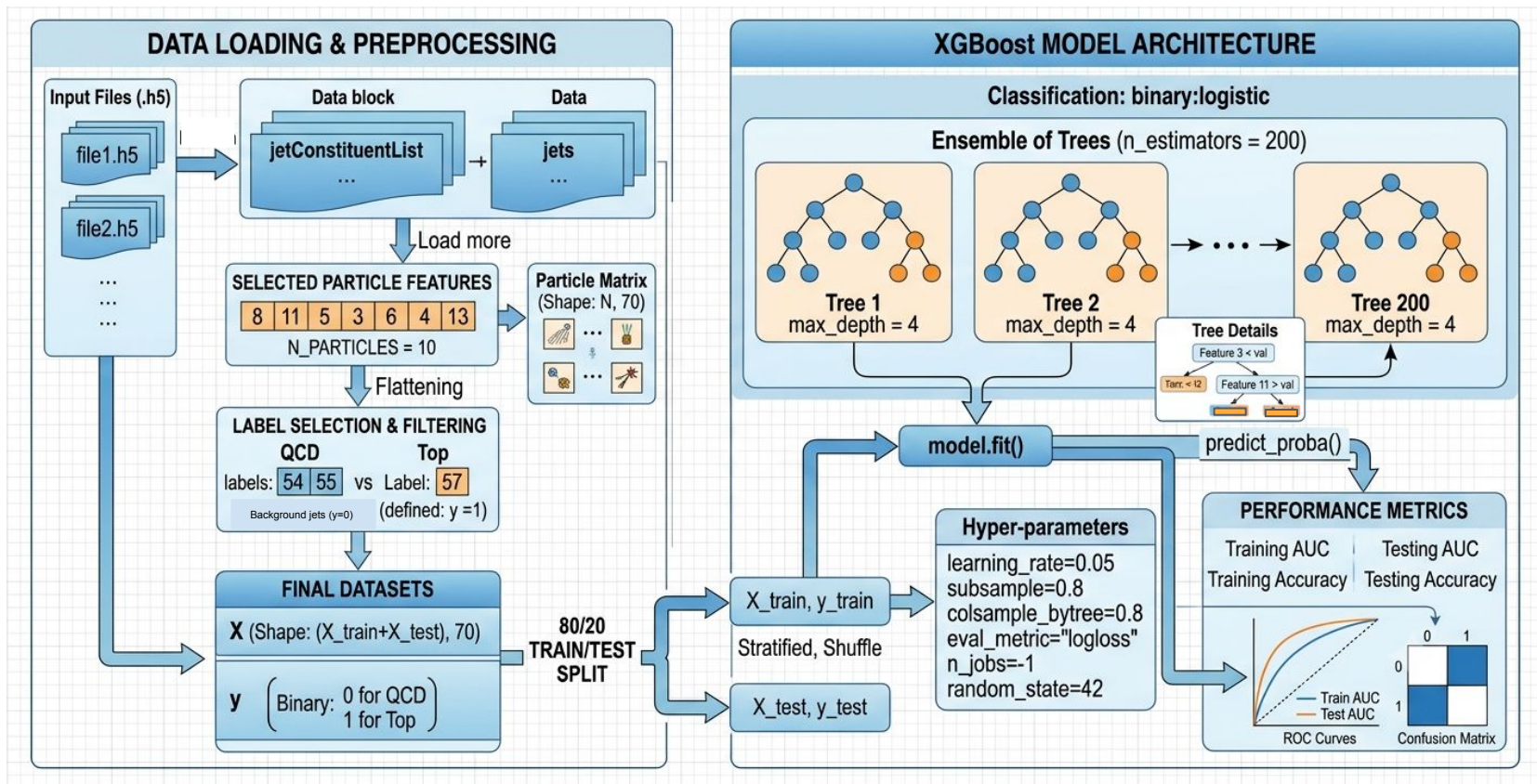
10 constituents
×
7 features
= 70 values

Flatten (10 × 7) row-wise → 70-dimensional Feature Vector

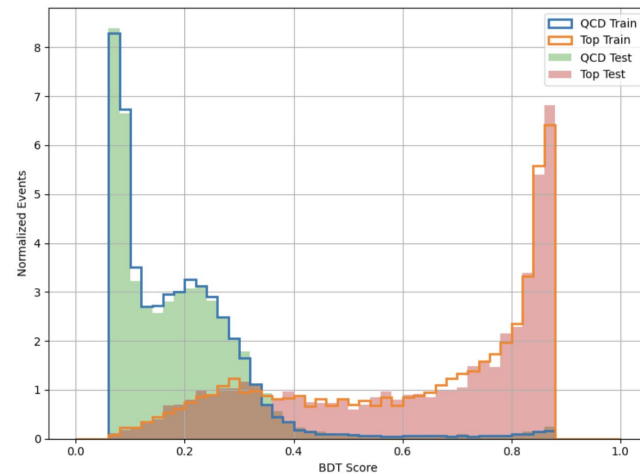
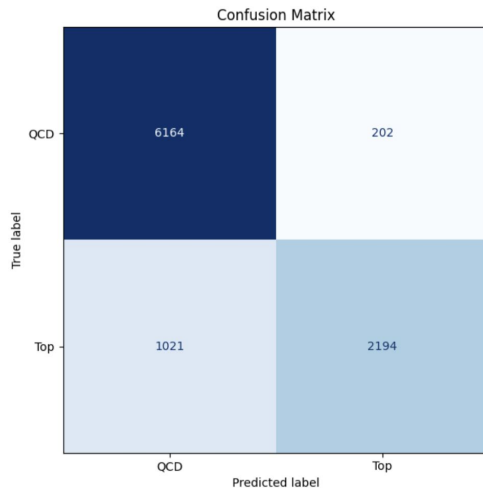
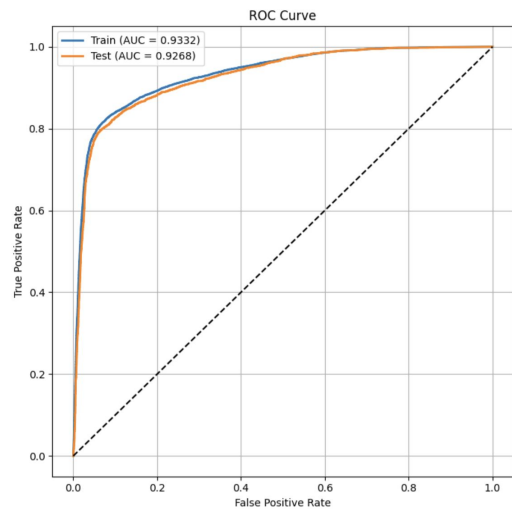
Feature (Col. Index)	8	11	5	3	6	4	13	8	11	5	3	6	4	13	...	8	11	5	3	6	4	13
Position in Vector	η_{rel}^1	ϕ_{rel}^1	p_T^1	E^1	p_{Trel}^1	E_{rel}^1	ΔR^1	η_{rel}^2	ϕ_{rel}^2	p_T^2	E^2	p_{Trel}^2	E_{rel}^2	ΔR^2	...	η_{rel}^{10}	ϕ_{rel}^{10}	p_T^{10}	E^{10}	p_{Trel}^{10}	E_{rel}^{10}	ΔR^{10}
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	...	64	65	66	67	68	69	70

70 values

BDT Architecture



BDT Results



Jets as Sets

Jet features:

```
[0] j_ptfrac
[1] j_pt
[2] j_eta
[3] j_mass
[4] j_tau1_b1
[5] j_tau2_b1
[6] j_tau3_b1
[7] j_tau1_b2
[8] j_tau2_b2
[9] j_tau3_b2
[10] j_tau32_b1
[11] j_tau32_b2
[12] j_zlogz
[13] j_c1_b0
[14] j_c1_b1
[15] j_c1_b2
[16] j_c2_b1
[17] j_c2_b2
```

Particle features:

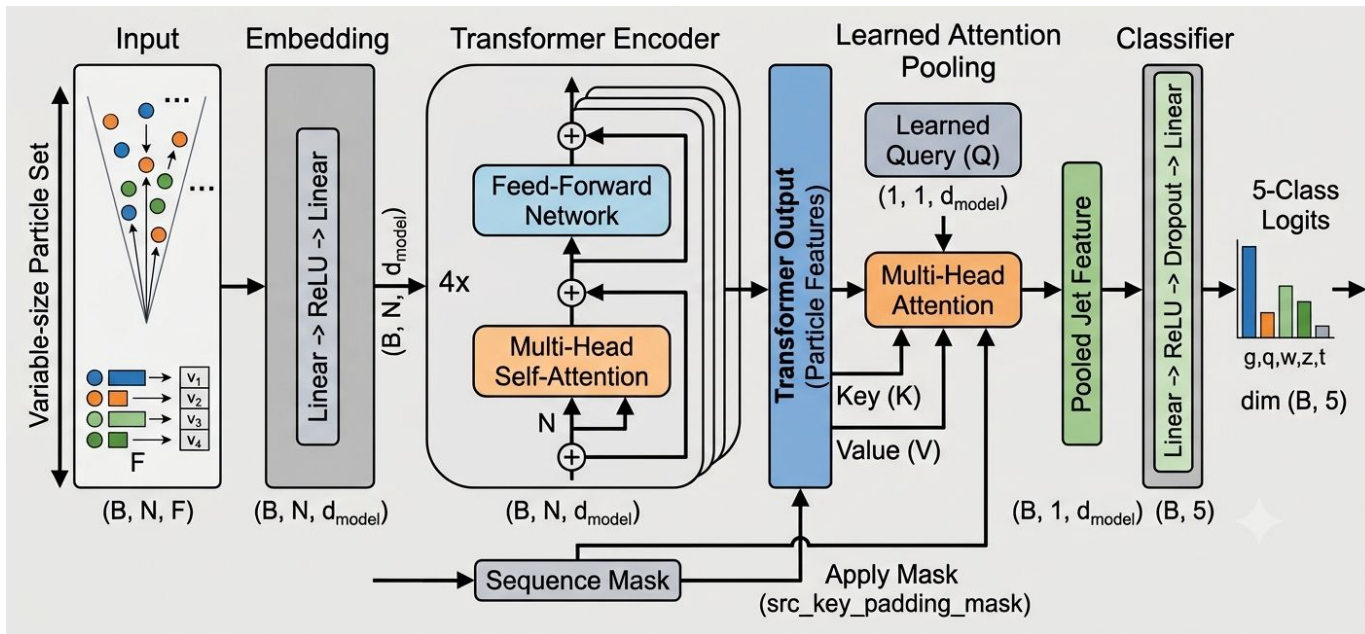
```
[0] j1_px
[1] j1_py
[2] j1_pz
[3] j1_e
[4] j1_ere1
[5] j1_pt
[6] j1_ptrel
[7] j1_eta
[8] j1_etarel
[9] j1_etarot
[10] j1_phi
[11] j1_phirel
[12] j1_phirot
[13] j1_deltaR
[14] j1_costheta
[15] j1_costhetarel
[16] j1_pdgid
```

```
jetConstituentList (10000, 100, 16) float64
jetFeatureNames (59,) object
jetImage (10000, 100, 100) float64
jetImageECAL (10000, 100, 100) float64
jetImageHCAL (10000, 100, 100) float64
jets (10000, 59) float64
particleFeatureNames (17,) object
```

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ΔR	angular separation between the particle and the jet axis ($\sqrt{(\Delta\eta)^2 + (\Delta\phi)^2}$)

<https://arxiv.org/abs/1902.08570>

Transformer Architecture

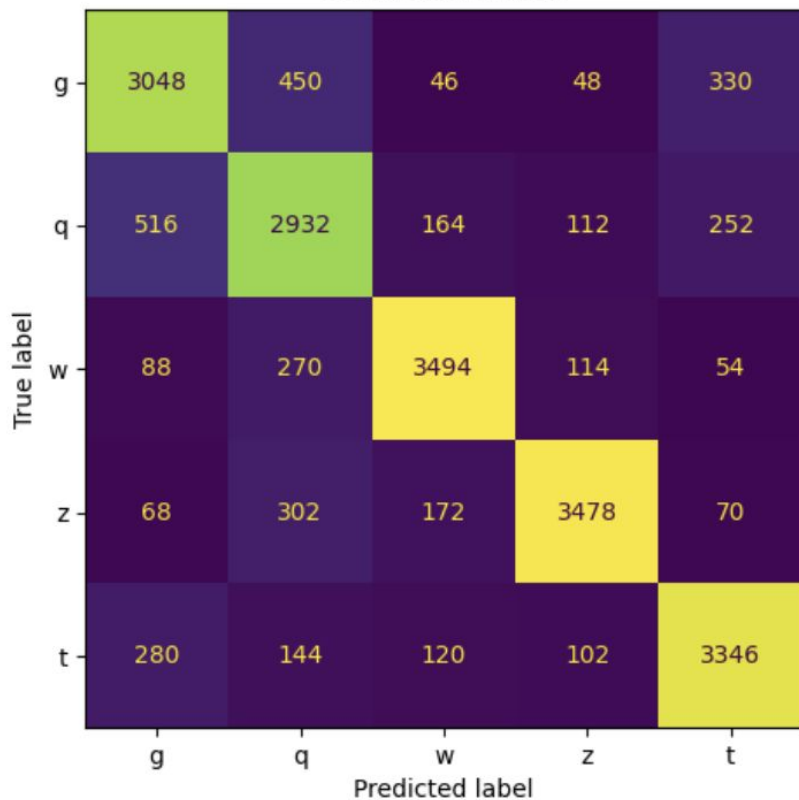


`N_EPOCHS = 200`
`PATIENCE = 10`
`d_model = 64`

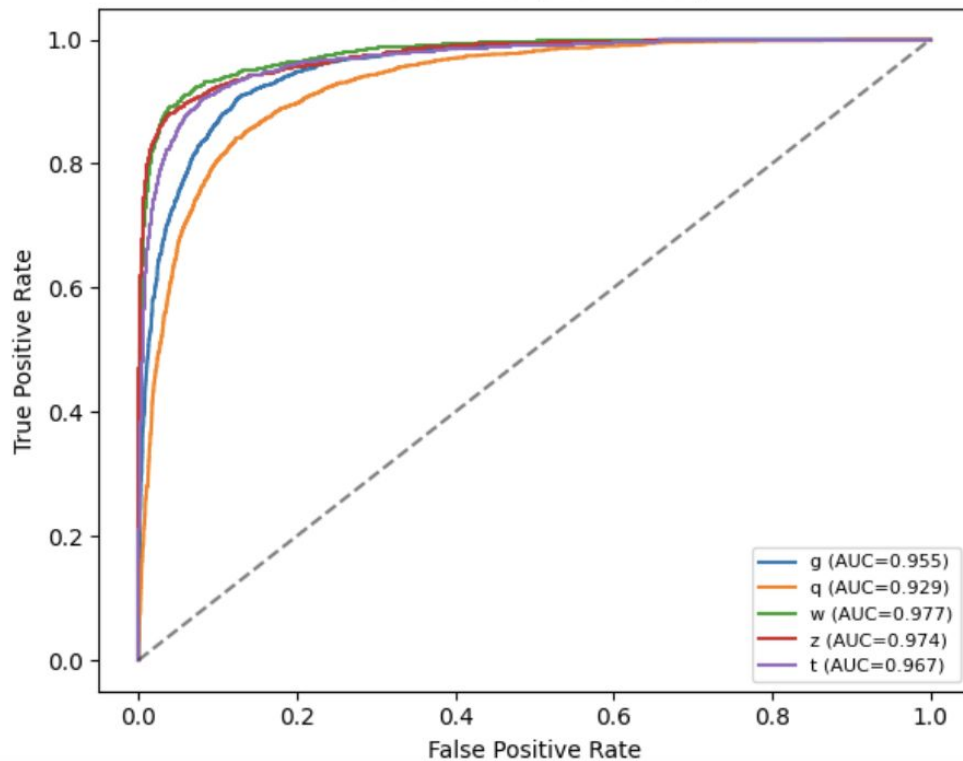
$$\mathcal{L} = -\log \left[\frac{e^{z_{\text{true}}}}{\sum_{i=1}^5 e^{z_i}} \right]$$

GNN-Transformer Results

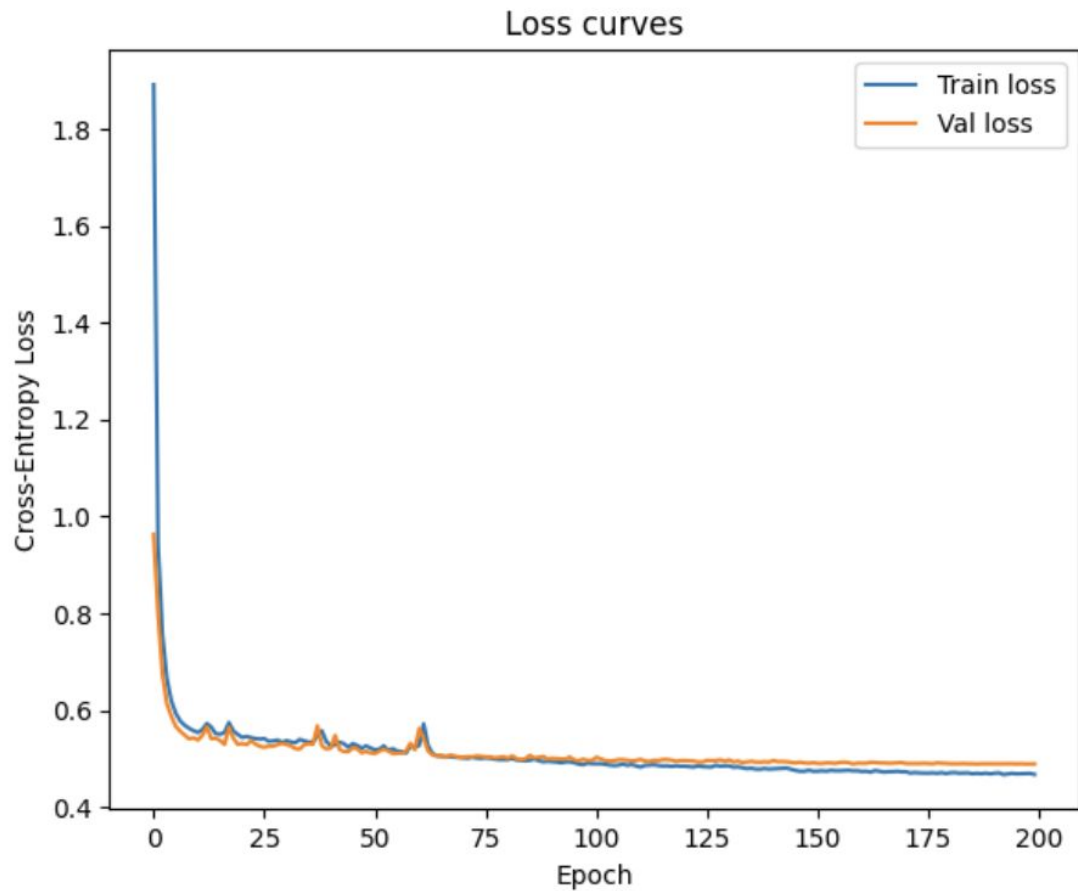
Confusion matrix



ROC curves (one-vs-rest)



No Overtraining!

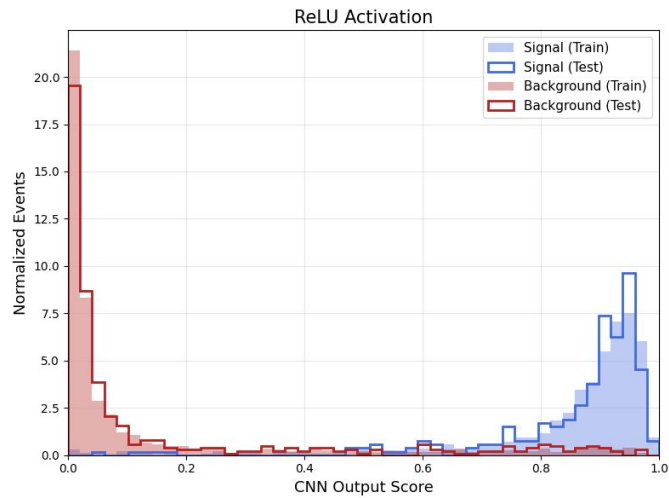
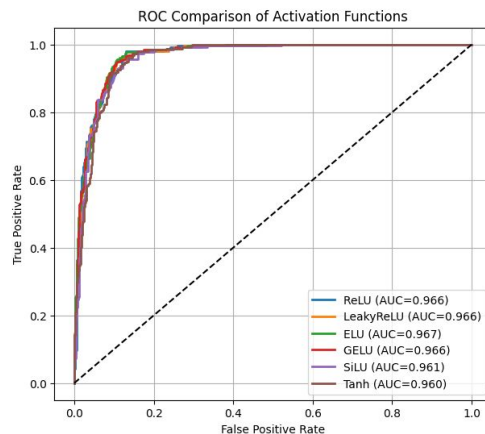
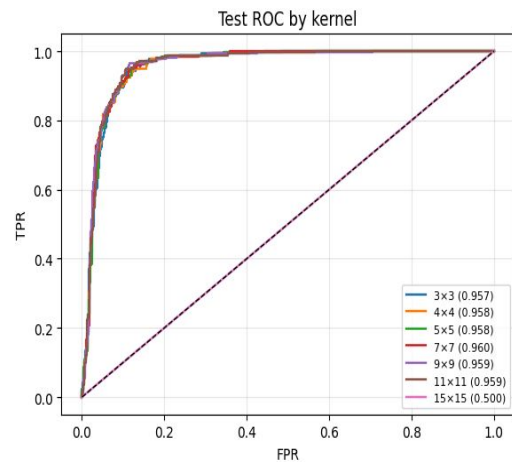


Summary

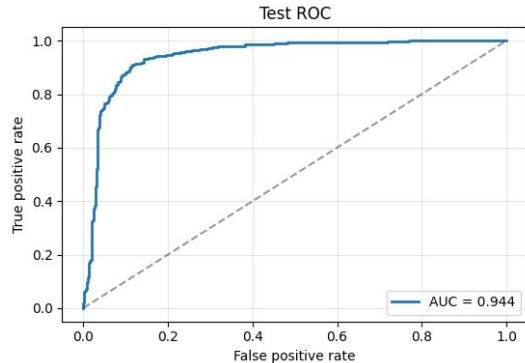
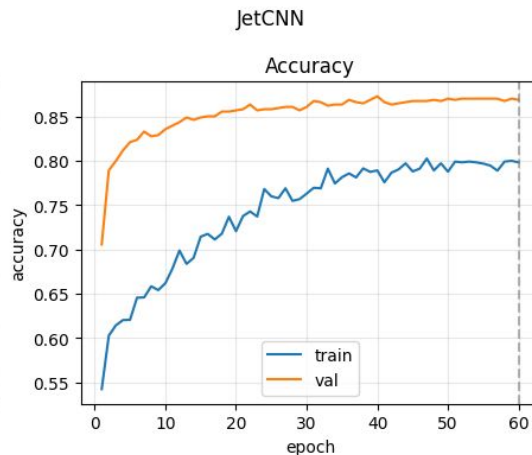
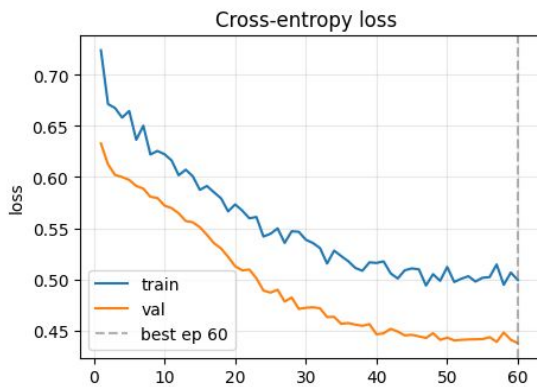
- Classify jets as per their sources using simulated datasets
- CNN - treat the jet as an image and classify the images into different labels
- BDT - treat the jet as a feature vector, and correct the decision boundaries on particle features to evaluate the class
- Transformer - treat the particles in a list as unordered sets and classify them into finer classes

Thank You!!

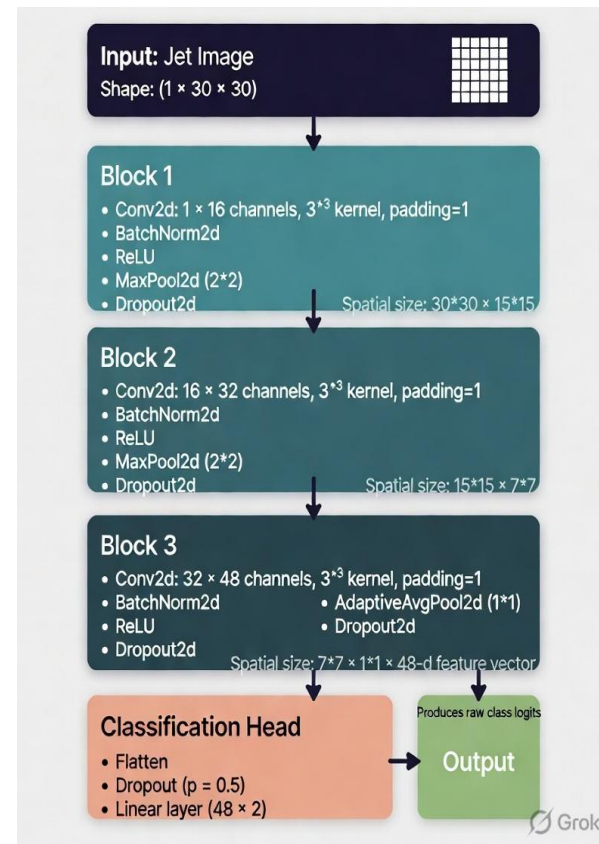
Sweep over architecture



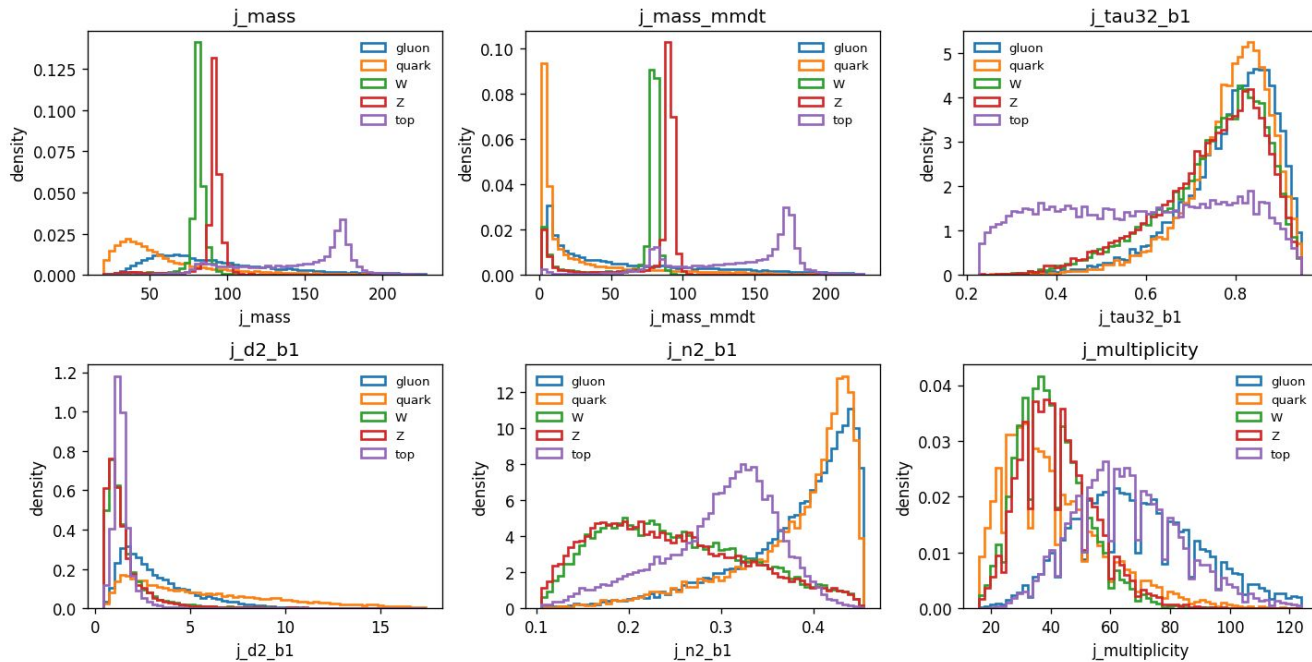
Architecture 2



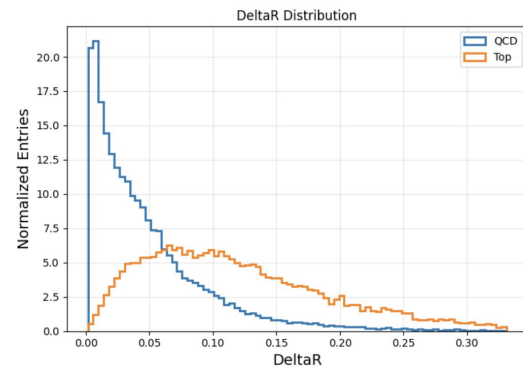
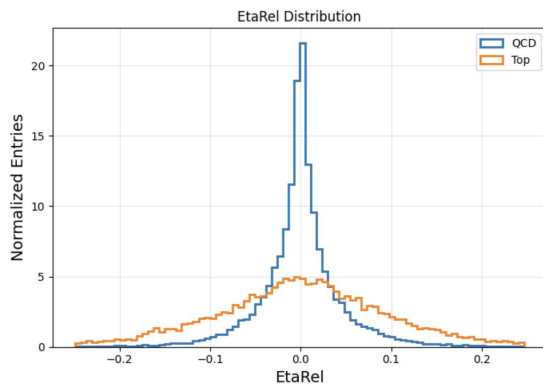
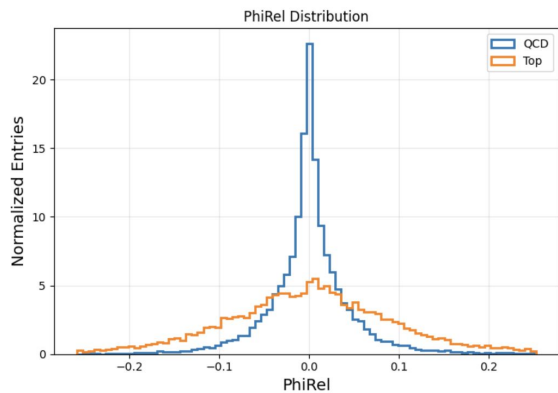
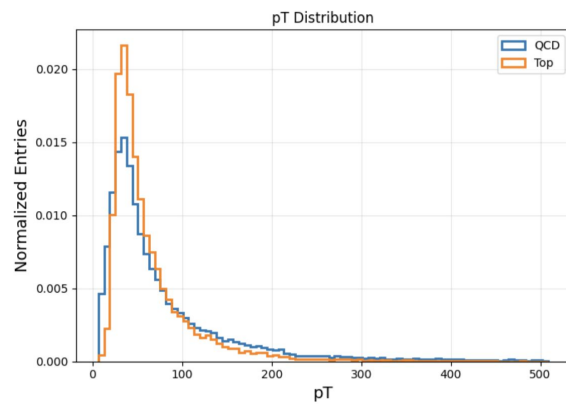
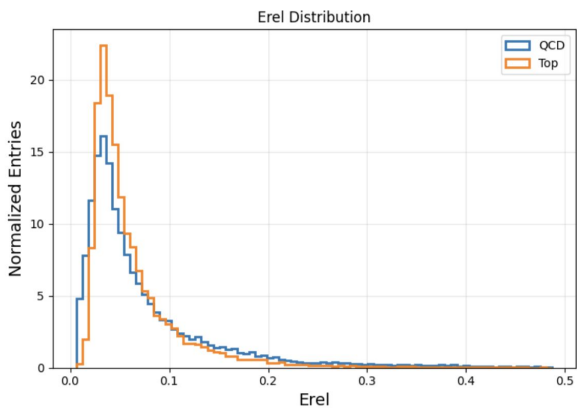
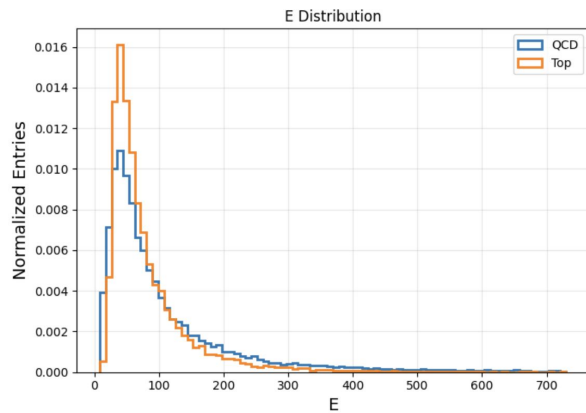
Trying different Arch



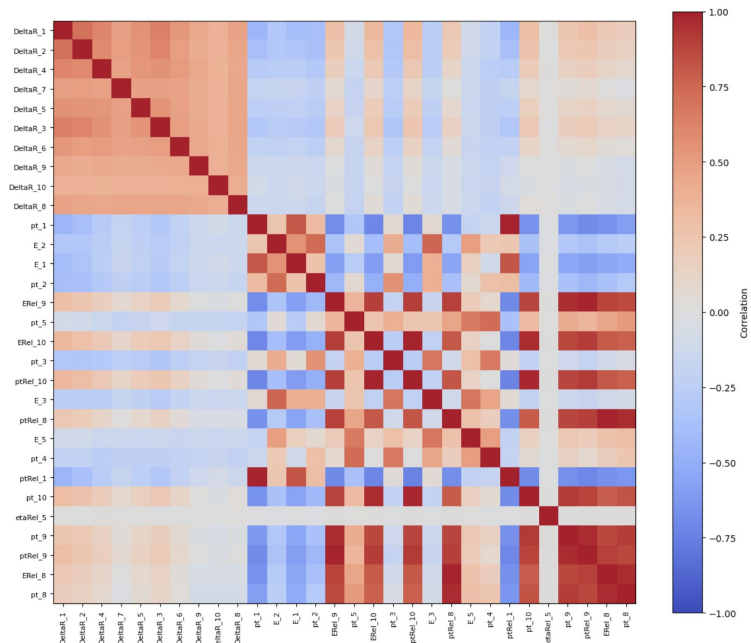
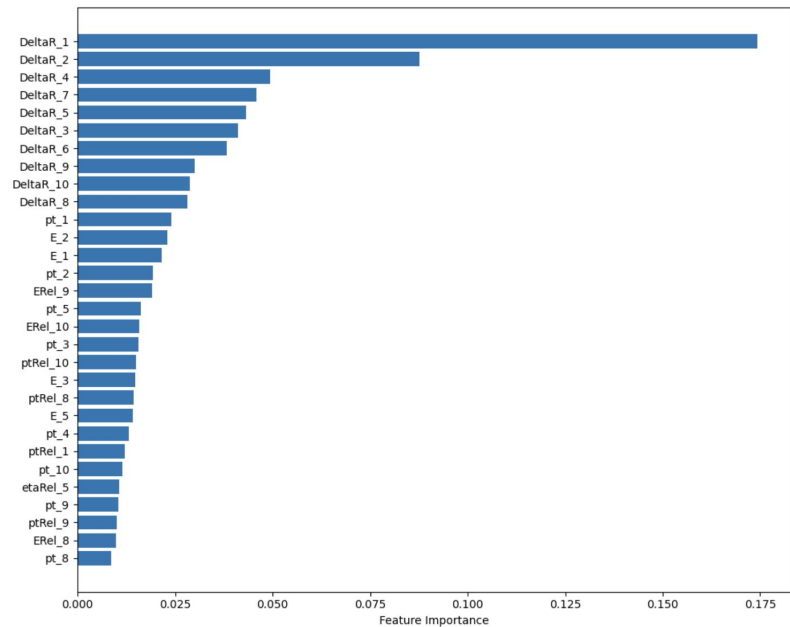
Key jet tagging features by class



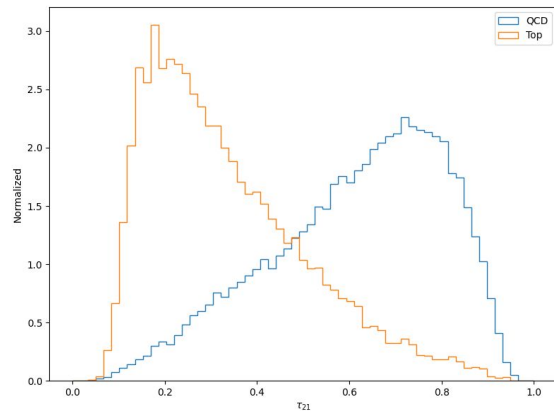
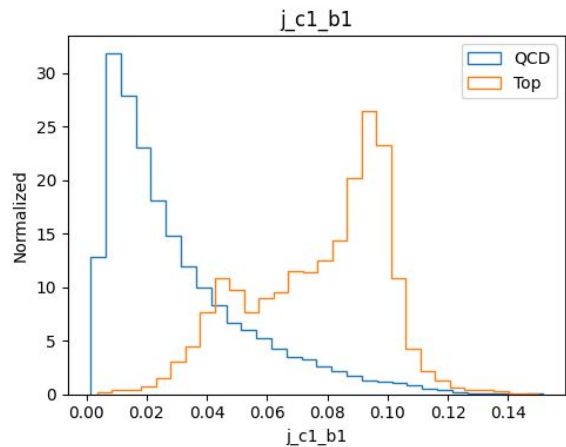
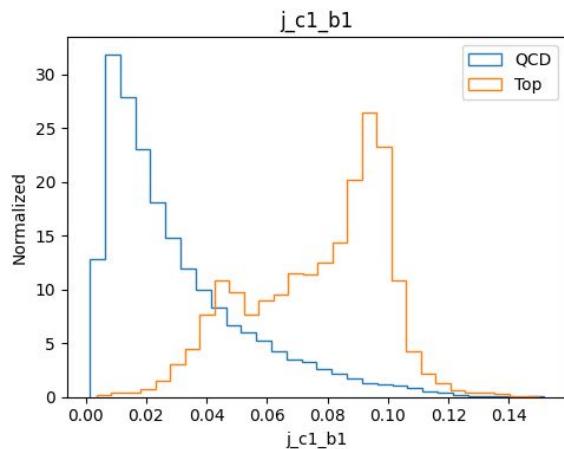
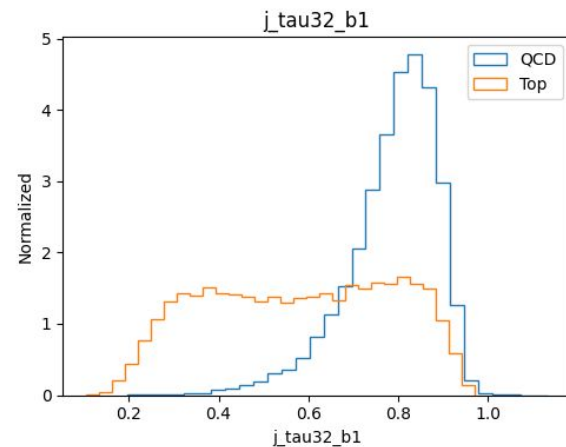
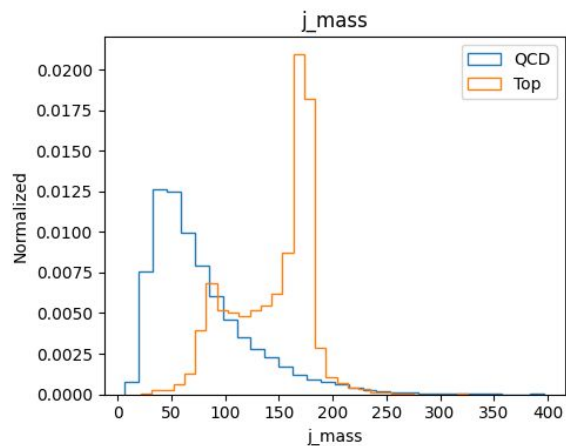
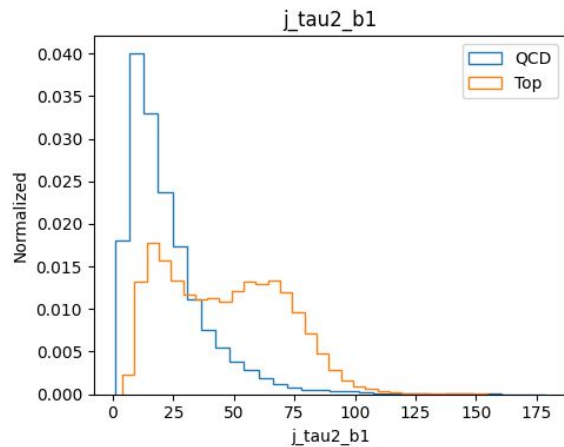
BDT



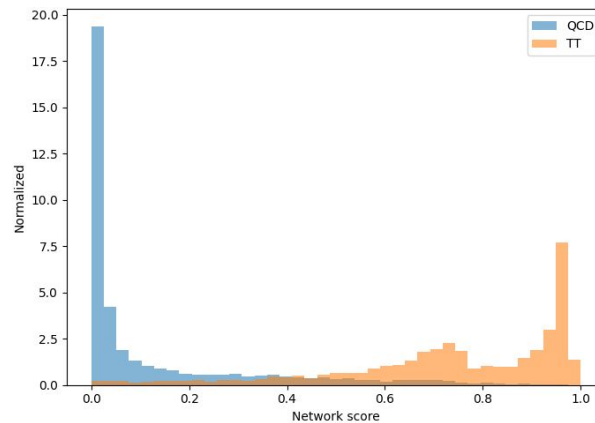
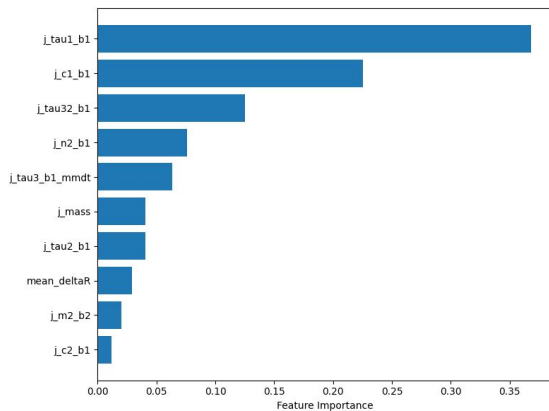
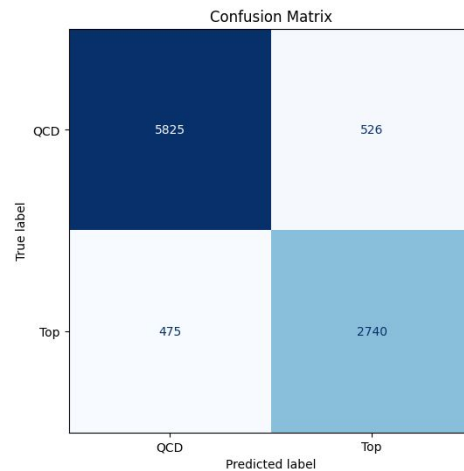
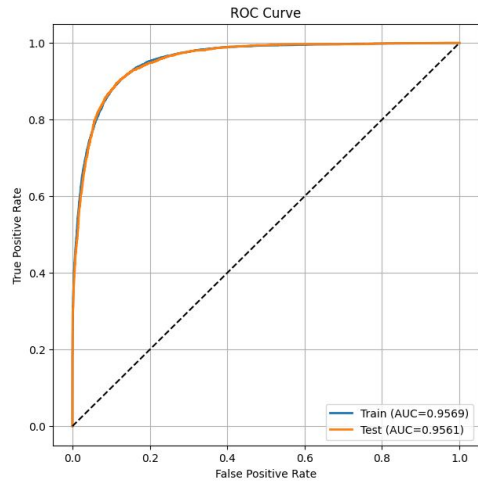
BDT



BDT using high level jet features



BDT using high level jet features



Query, Key, Value Architecture

1 · From hard k-NN edges to soft attention

Write a GNN layer and an attention layer side by side:

$$\text{GNN: } h'_i = \phi\left(h_i, \bigoplus_{j \in \mathcal{N}(i)} \psi(h_i, h_j)\right) \quad \text{Attention: } h'_i = \sum_j \alpha_{ij} v_j, \quad \alpha_{ij} = \frac{\exp(q_i \cdot k_j / \sqrt{d})}{\sum_{j'} \exp(q_i \cdot k_{j'} / \sqrt{d})}$$

The only differences: the neighbourhood is **all** particles, and the "edge weight" α_{ij} is **learned and soft** (a probability) rather than a 0/1 k-NN membership. So a Transformer is a GNN on a **fully-connected graph with a learned, normalized, per-layer adjacency**. Everything you know from Module 2 transfers.

Because the sum over j is permutation-invariant, attention on a *set* needs **no positional encoding** — and that is exactly what we want for particles, which have no canonical order.

2 · Scaled dot-product attention

Given queries Q , keys K , values V (each a matrix with one row per particle):

$$\text{Attention}(Q, K, V) = \text{softmax}\left(\frac{QK^\top}{\sqrt{d_k}}\right) V.$$

- $QK^\top$ scores how much particle i (query) cares about particle j (key);
- $\sqrt{d_k}$ keeps the scores from blowing up with dimension;
- softmax turns each row into attention weights $\alpha_{i\cdot}$ that sum to 1;
- multiplying by V returns a weighted average of the value vectors.

We must **mask padded particles**: their key columns get $-\infty$ before the softmax so nobody attends to them.